## SUMMARY OF LAPLACE TRANSFORMS

1. Methods of solution

Method. To solve an IVP:

- 1) Take the Laplace transform of the differential equation;
- 2) Use the initial conditions;
- 3) Solve for Y = L(y) (do as little algebra as possible);
- 4) Take the inverse Laplace transform to find the solution.

**Method.** To solve an IVP of the form  $ay'' + by' + cy = f(t) + \alpha\delta(t - t_0)$ ,  $y(0) = k_0$ ,  $y'(0) = k_1$ :

- 1) Find a solution  $\hat{y}(t)$  to the IVP ay'' + by' + cy = f(t),  $y(0) = k_0$ ,  $y'(0) = k_1$  (use any method);
- 2) Find the impulse response w(t) of  $ay'' + by' + cy = \delta(t t_0)$  (definition below);
- 3) The solution to the original IVP is  $y(t) = \hat{y}(t) + \alpha u(t t_0)w(t t_0)$

**Theorem.** Let  $t_0 \ge 0$ . The solution to the IVP  $ay'' + by' + cy = \delta(t - t_0)$ , y(0) = 0, y'(0) = 0, is  $y = u(t - t_0)w(t - t_0)$  where  $w(t) = L^{-1}\left(\frac{1}{as^2 + bs + c}\right)$  (w(t) is the **impulse response** of the system).

## 2. Theorems for Laplace transforms

**Theorem.** Suppose f and f' are continuous on  $[0, \infty)$  and of exponential order  $s_0$ , and that f'' is piecewise continuous on  $[0, \infty)$ . Then f, f', and f'' have Laplace transforms for  $s > s_0$ :

$$L(f') = sL(f) - f(0)$$
 and  $L(f'') = s^2L(f) - sf(0) - f'(0)$ 

**Theorem** (Linearity). Let  $c_1, c_2, \ldots, c_n$  be constants and let  $f_1, f_2, \ldots, f_n$  and  $F_1, F_2, \ldots, F_n$  be functions. Then

$$L(c_1f_1 + c_2f_2 + \dots + c_nf_n) = c_1L(f_1) + c_2L(f_2) + \dots + c_nL(f_n)$$

and

$$L^{-1}(c_1F_1 + c_2F_2 + \dots + c_nF_n) = c_1L^{-1}(F_1) + c_2L^{-1}(F_2) + \dots + c_nL^{-1}(F_n)$$

**Theorem** (Superposition). If  $y_1$  is the solution of the IVP

$$ay'' + by' + cy = f_1(t), \ y(0) = k_1, \ y'(0) = k_2$$

and  $y_2$  is the solution of the IVP

$$ay'' + by' + cy = f_2(t), \ y(0) = l_1, \ y'(0) = l_2$$

then  $y_1 + y_2$  is the solution to the IVP

$$ay'' + by' + cy = f_1(t) + f_2(t), \ y(0) = k_1 + l_1, \ y'(0) = k_2 + l_2$$

**Theorem** (First Shifting Theorem). If L(f(t)) = F(s) for  $s > s_0$ , then  $L(e^{at}f(t)) = F(s-a)$  for  $s > s_0 + a$ .

**Theorem** (Second shifting theorem).  $L^{-1}(e^{-st_0}L(g(t))) = u(t-t_0)g(t-t_0)$ 

**Theorem.** If  $t_0 \ge 0$  and  $L(g(t+t_0))$  exists for  $s > s_0$ , then  $L(u(t-t_0)g(t)) = e^{-st_0}L(g(t+t_0))$  for  $s > s_0$ .

**Theorem** (Convolution Theorem). L(f \* g) = L(f)L(g)

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**Definition.** The unit step function (or Heaviside function) is  $u(t) = \begin{cases} 0 & \text{if } t < 0 \\ 1 & \text{if } t \ge 0 \end{cases}$ 

**Method.** The piecewise function  $f(t) = \begin{cases} g(t) & \text{if } t < t_1 \\ h(t) & \text{if } t \ge t_1 \end{cases}$  can be expressed as  $f(t) = g(t) + u(t - t_1) \left[ h(t) - g(t) \right]$ 

**Definition.** Let f and g be functions such that if t < 0, then f(t) = 0 and g(t) = 0. The **convolution** of f and g is the function f \* g defined by

$$(f * g)(t) = \int_0^t f(\tau)g(t - \tau)d\tau$$

**Definition.** The **Dirac delta** (or **unit impulse**) function is defined to be the "function"  $\delta(t)$  such that

(1) 
$$\delta(t) = 0$$
 if  $t \neq 0$   
(2)  $\int_{\infty}^{\infty} \delta(t) dt = 1$ 

Note that there is no real number y such that  $\delta(0) = y$ .

**Definition.** The Laplace transform of f(t) is  $\int_0^\infty e^{-st} f(t) dt$ . Note, however, that this is rarely used. Instead, refer to the a table of Laplace transforms (see section 8.8 of the textbook).