

## 1 Methods of solution

**Method.** To solve an IVP not involving the Dirac delta function:

1. Take the Laplace transform of the differential equation;
2. Use the initial conditions;
3. Solve for  $Y = L(y)$  (do as little algebra as possible);
4. Take the inverse Laplace transform to find your solution  $y$ .

**Method.** To solve an IVP of the form  $ay'' + by' + cy = f(t) + \alpha\delta(t - t_0)$ ,  $y(0) = k_0$ ,  $y'(0) = k_1$ :

1. Find a solution  $\hat{y}(t)$  to the IVP  $ay'' + by' + cy = f(t)$ ,  $y(0) = k_0$ ,  $y'(0) = k_1$  (use any method);
2. Find the impulse response  $w(t)$  of  $ay'' + by' + cy = \delta(t - t_0)$ ,  $y(0) = 0$ ,  $y'(0) = 0$  (definition follows);
3. The solution to the original IVP is  $y(t) = \hat{y}(t) + \alpha u(t - t_0)w(t - t_0)$ .

**Theorem.** If  $t_0 > 0$ , then the solution to the IVP  $ay'' + by' + cy = \delta(t - t_0)$ ,  $y(0) = 0$ ,  $y'(0) = 0$ , is

$$y = u(t - t_0)w(t - t_0) \quad \text{where} \quad w(t) = L^{-1}\left(\frac{1}{as^2 + bs + c}\right) \quad (w(t) \text{ is the impulse response of the system}).$$

## 2 Theorems for Laplace transforms

**Theorem.** Suppose  $f$  and  $f'$  are continuous on  $[0, \infty)$  and of exponential order  $s_0$ , and that  $f''$  is piecewise continuous on  $[0, \infty)$ . Then  $f$ ,  $f'$ , and  $f''$  have Laplace transforms for  $s > s_0$ :

$$L(f') = sL(f) - f(0) \quad \text{and} \quad L(f'') = s^2L(f) - sf(0) - f'(0)$$

**Theorem (Linearity Property).** Let  $c_1, c_2, \dots, c_n$  be constants and let  $F_1, F_2, \dots, F_n$  be functions. Then

$$L^{-1}(c_1F_1 + c_2F_2 + \dots + c_nF_n) = c_1L^{-1}(F_1) + c_2L^{-1}(F_2) + \dots + c_nL^{-1}(F_n)$$

**Theorem (Superposition).** If  $y_1$  is the solution of the IVP

$$ay'' + by' + cy = f_1(t), \quad y(0) = k_1, \quad y'(0) = k_2$$

and  $y_2$  is the solution of the IVP

$$ay'' + by' + cy = f_2(t), \quad y(0) = l_1, \quad y'(0) = l_2,$$

then  $y_1 + y_2$  is the solution to the IVP

$$ay'' + by' + cy = f_1(t) + f_2(t), \quad y(0) = k_1 + l_1, \quad y'(0) = k_2 + l_2.$$

**Theorem (First Shifting Theorem).** If  $L(f(t)) = F(s)$  for  $s > s_0$ , then  $L(e^{at}f(t)) = F(s - a)$  for  $s > s_0 + a$ .

**Theorem (Second shifting theorem).**  $e^{-st_0}L(g(t)) = L(u(t - t_0)g(t - t_0))$

**Theorem.** If  $t_0 \geq 0$  and  $L(g(t + t_0))$  exists for  $s > s_0$ , then  $L(u(t - t_0)g(t)) = e^{-st_0}L(g(t + t_0))$  for  $s > s_0$ .

**Theorem (Convolution Theorem).**  $L(f * g) = L(f)L(g)$

### 3 Special functions and operations

**Definition.** The **unit step function** is  $u(t) = \begin{cases} 0 & \text{if } t < 0 \\ 1 & \text{if } t \geq 0 \end{cases}$

**Method.** The piecewise function  $f(t) = \begin{cases} g(t) & \text{if } t < t_1 \\ h(t) & \text{if } t \geq t_1 \end{cases}$  can be expressed as

$$f(t) = g(t) + u(t - t_1) [h(t) - g(t)]$$

**Definition.** Let  $f$  and  $g$  be functions such that if  $t < 0$ , then  $f(t) = 0$  and  $g(t) = 0$ . The **convolution** of  $f$  and  $g$  is the function  $f * g$  defined by

$$(f * g)(t) = \int_0^t f(\tau)g(t - \tau)d\tau$$

**Definition.** The **Dirac delta** (or **unit impulse**) function is defined to be the “function”  $\delta(t)$  such that

1.  $\delta(t) = 0$  if  $t \neq 0$

2.  $\int_{-\infty}^{\infty} \delta(t)dt = 1$

Note that there is no real number  $y$  such that  $\delta(0) = y$ .

**Definition.** The **Laplace transform** of  $f(t)$  is  $\int_0^{\infty} e^{-st} f(t)dt$ . Note, however, that this is rarely used. Instead, refer to the a table of Laplace transforms (see section 8.8 of the textbook).